

Leveraging **Self-Consistency** for Data-Efficient **Amortized Bayesian Inference**

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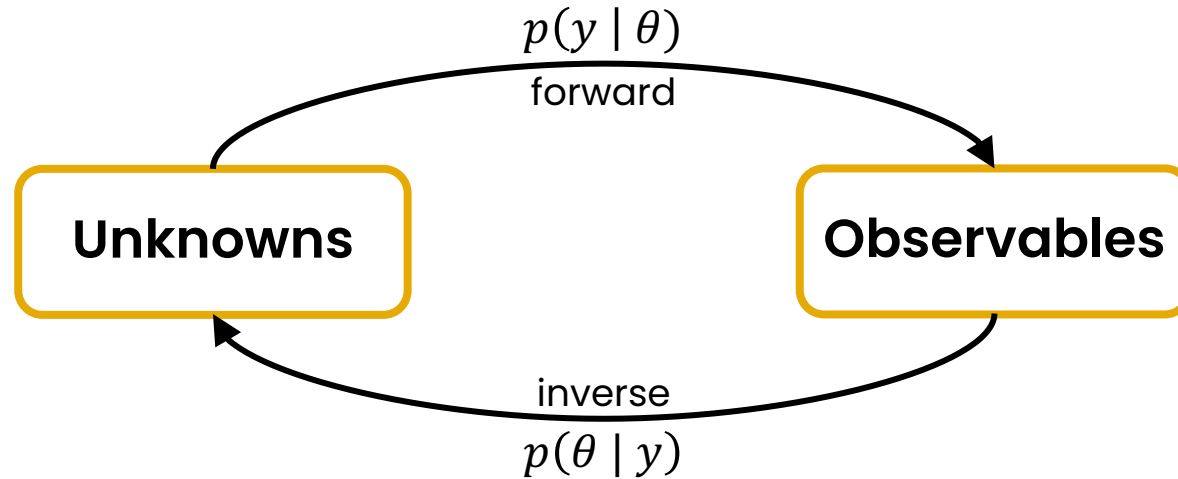
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Inverse Problems



Statistical modeling: **Parameters θ**

Data y

Epidemiology: Virus attributes

Infection curve (time series)

Image processing: Crisp image

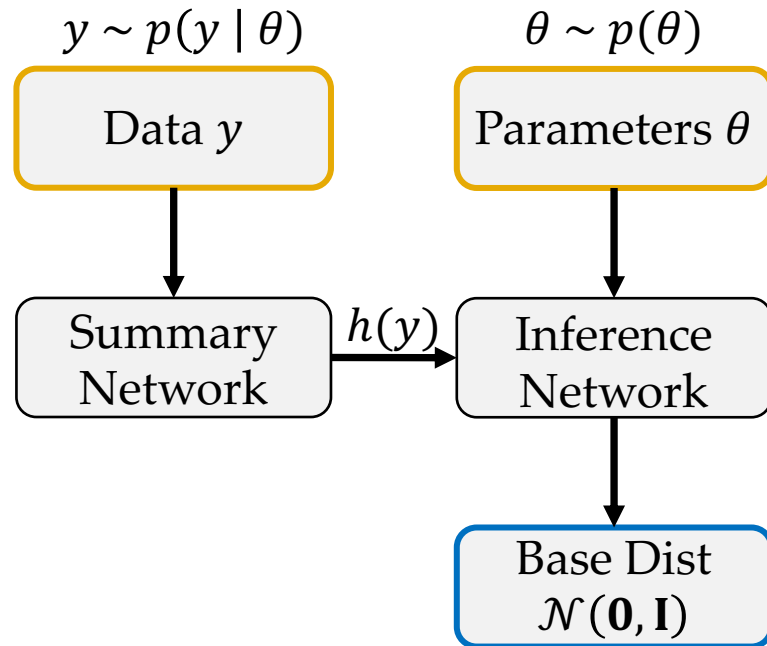
Blurry image

Psychology: Cognitive parameters

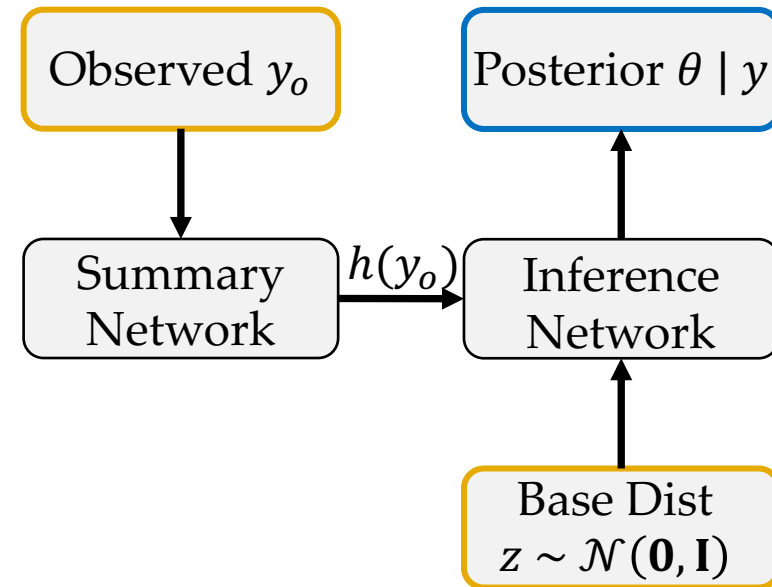
Reaction times

Amortized Bayesian Inference

Stage 1: Training *potentially expensive*

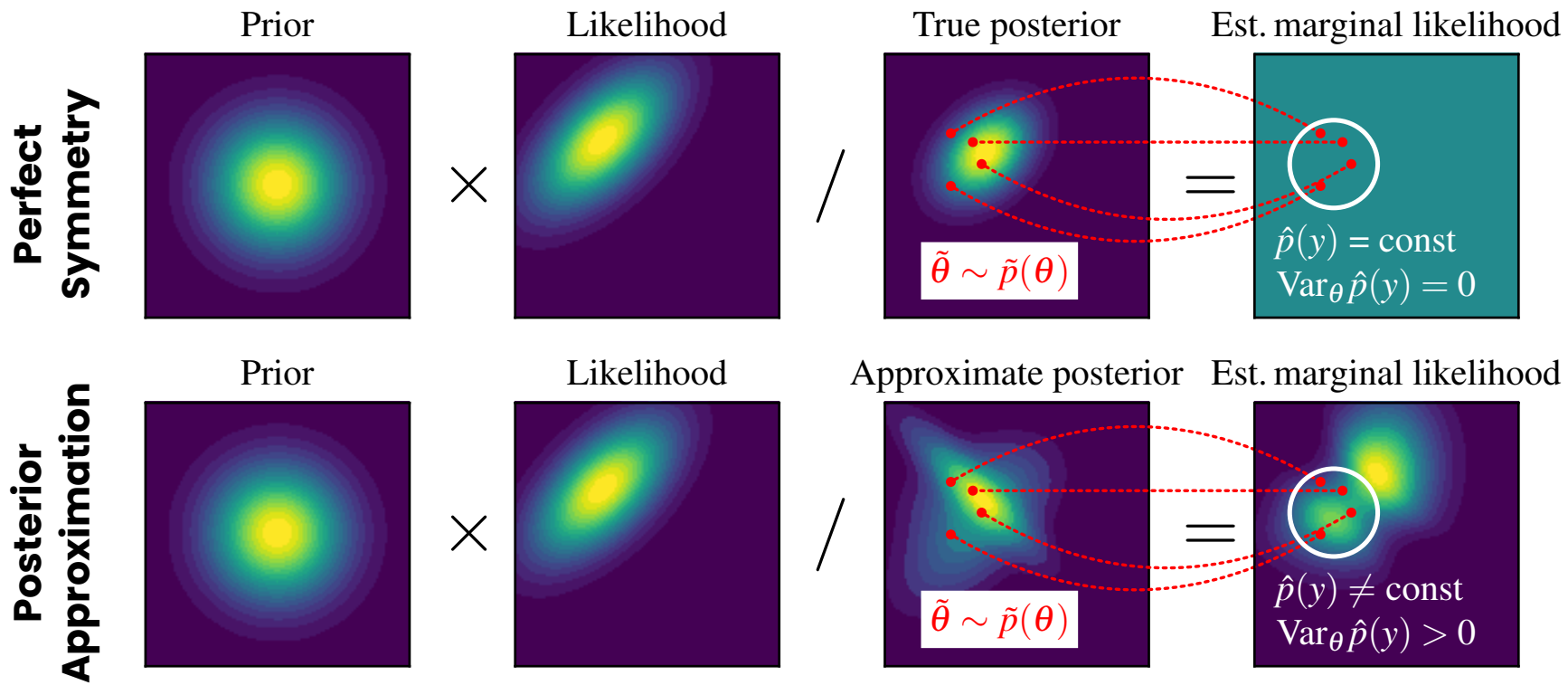


Stage 2: Inference *amortized over many y_o*



Self-Consistency Property

$$p(y) = p(\theta) p(y | \theta) / p(\theta | y) \implies \frac{p(\tilde{\theta}_1) p(y | \tilde{\theta}_1)}{p(\tilde{\theta}_1 | y)} = \dots = \frac{p(\tilde{\theta}_K) p(y | \tilde{\theta}_K)}{p(\tilde{\theta}_K | y)} \quad \tilde{\theta}_1, \dots, \tilde{\theta}_K \in \Theta$$



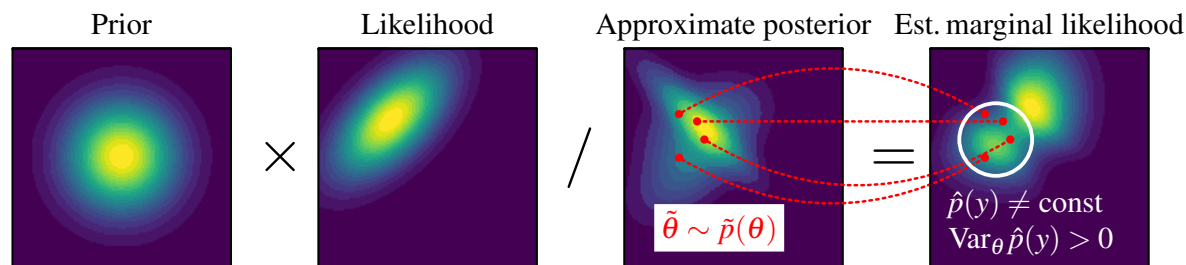
Self-Consistency Loss

- Idea: Violations of self-consistency property as loss function

$$\mathcal{L}_{\text{SC}} := \mathbb{E}_{p(y)} \left[\text{Var}_{\tilde{\theta} \sim \tilde{p}(\theta)} \left(\log p(\tilde{\theta}) + \log p(y | \tilde{\theta}) - \log q_{\phi}(\tilde{\theta} | y) \right) \right]$$

- Integration into standard neural posterior estimation loss

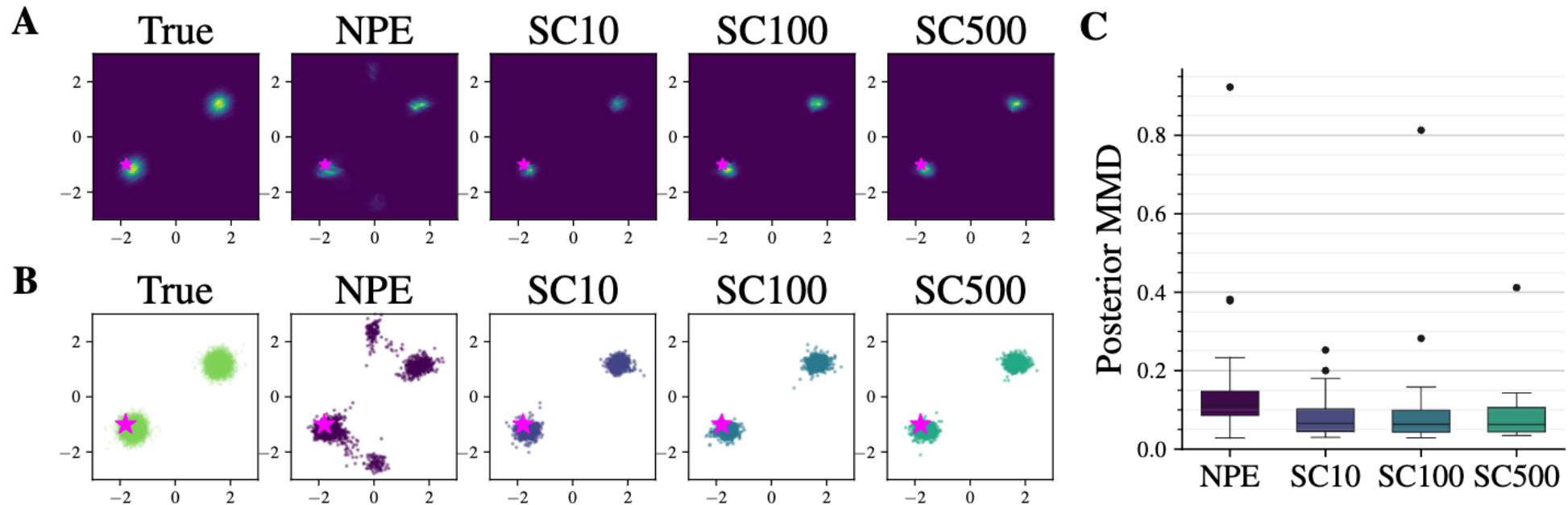
$$\mathcal{L}_{\text{NPE-SC}} := \mathbb{E}_{p(y)} \left[\underbrace{\mathbb{E}_{p(\theta | y)} [-\log q_{\phi}(\theta | y)]}_{\text{NPE loss}} + \underbrace{\lambda \text{Var}_{\tilde{\theta} \sim \tilde{p}(\theta)} \left(\log p(\tilde{\theta}) + \log p(y | \tilde{\theta}) - \log q_{\phi}(\tilde{\theta} | y) \right)}_{\text{self-consistency loss } \mathcal{L}_{\text{SC}} \text{ with weight } \lambda \in \mathbb{R}_+} \right]$$



Experiment 1: Gaussian Mixture

Posterior estimation, $N = 1024$ training budget

- Model: $\theta \sim \mathcal{N}(\theta | \mathbf{0}, \mathbf{I})$, $y \sim 0.5 \mathcal{N}(y | \theta, \mathbf{I}/2) + 0.5 \mathcal{N}(y | -\theta, \mathbf{I}/2)$
- Results: Better density and sampling compared to default (NPE)

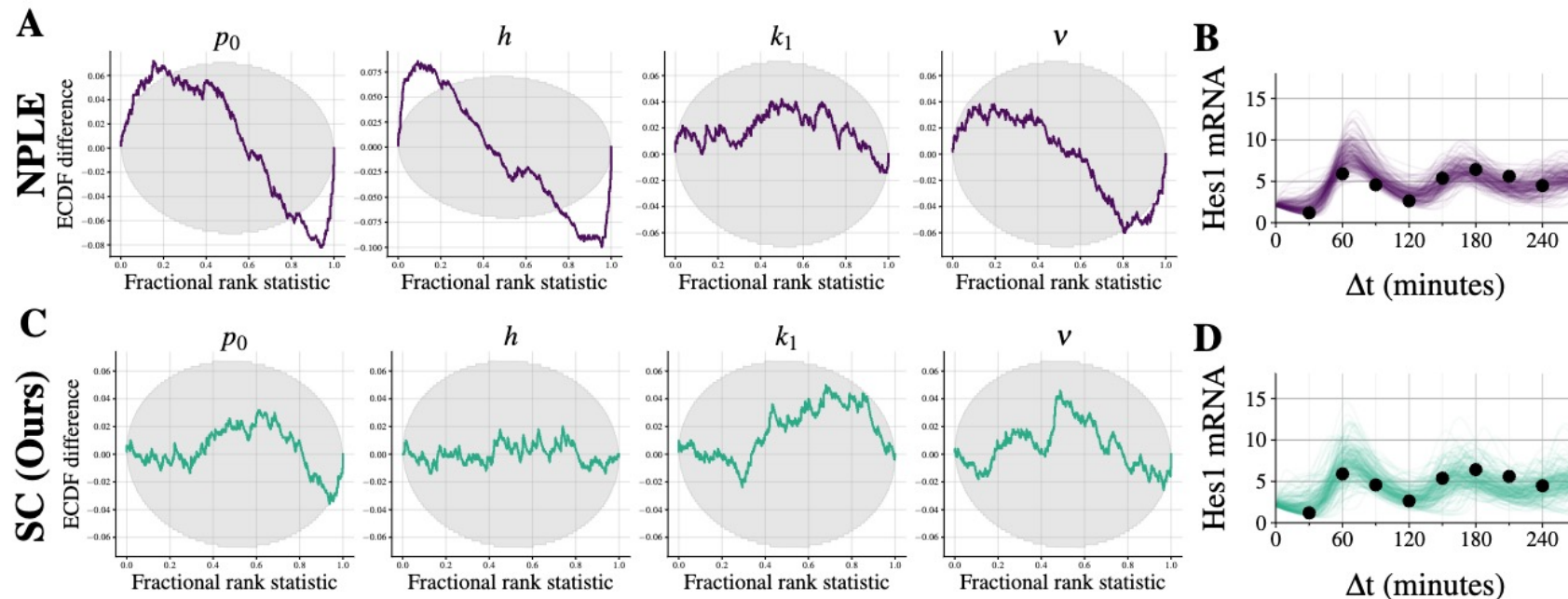


Experiment 2: Hes1 Expression Model

Posterior and likelihood estimation, $N = 512$ training budget

Results:

- Better simulation-based calibration (SBC; Talts et al., 2018)
- Similar posterior predictive results



Conclusion & Next Steps

Achievements

- Better posterior estimation in low-data settings
- Straightforward integration of the additive self-consistency loss

Next steps

- Explore better and more stable self-consistency training schemes
- Push the envelope on training/inference without ground-truths
- Potential for out-of-distribution settings?

Contact



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