

# Bayesian Probabilistic Modeling for Ecology

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**You are a Bayesian if you quantify uncertainty  
with probability**

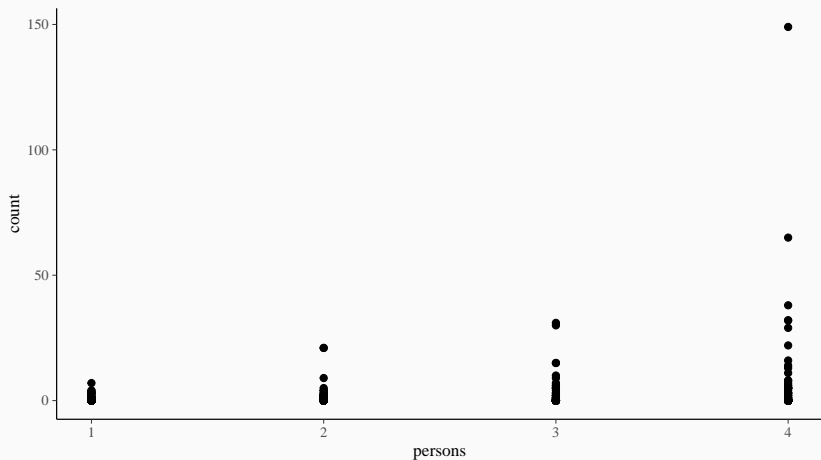
# The Bayes Theorem

$$p(\theta | y) = \frac{p(y | \theta) p(\theta)}{p(y)}$$

# Rethinking the Bayes Theorem

$$p(\theta | y) \propto p(y | \theta) p(\theta) = p(y, \theta)$$

# Example: Catching Fish



# Catching Fish: Modeling

Likelihood:

$$p(y_n | \theta) = \text{Poisson}(\exp(\theta_1 + \theta_2 x_n))$$

Example weakly informative priors:

$$p(\theta_1) = \text{normal}(0, 3), \quad p(\theta_2) = \text{normal}(0, 1)$$

Flat (“uninformative”) priors:

$$\theta_1 \propto 1, \quad \theta_2 \propto 1$$

Joint model:

$$p(y, \theta) = \left( \prod_n^N p(y_n | \theta) \right) p(\theta_1) p(\theta_2)$$

# The Innocent Marginal Likelihood

$$p(y) = \int p(y \mid \theta) p(\theta) d\theta$$

# Expectations to summarize distributions

**(Almost) all we care about are expectations**

Expectation of some function  $f$  over the posterior  $p(\theta | y)$ :

$$\mathbb{E}_{\theta|y}(f) = \int f(\theta) p(\theta | y) d\theta$$

Things that are (behave like) expectations:

- Mean
- Variance / standard deviation
- Median
- Other quantiles



**Samples can be used to approximate expectations**

Having obtained  $S$  random samples  $\{\theta^{(s)}\}$  from  $p(\theta | y)$ :

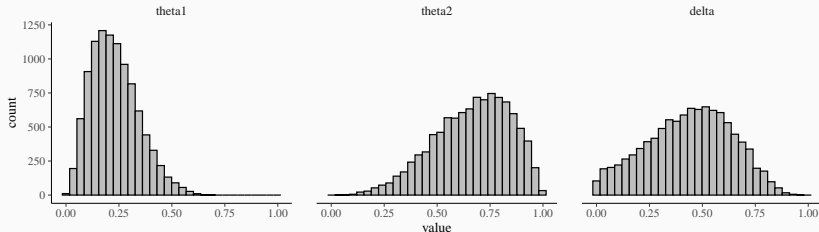
$$\frac{1}{S} \sum_{s=1}^S f(\theta^{(s)}) \sim \text{Normal} \left( \mathbb{E}_{\theta|y}(f), \sqrt{\frac{\text{Var}_{\theta|y}(f)}{S}} \right)$$

# Propagation of Uncertainty

## Uncertainty can be propagated easily using samples

Suppose, we are interesting in the posterior of  $\delta = |\theta_1 - \theta_2|$

Just evaluate  $\delta^{(s)} = |\theta_1^{(s)} - \theta_2^{(s)}|$  per sample:



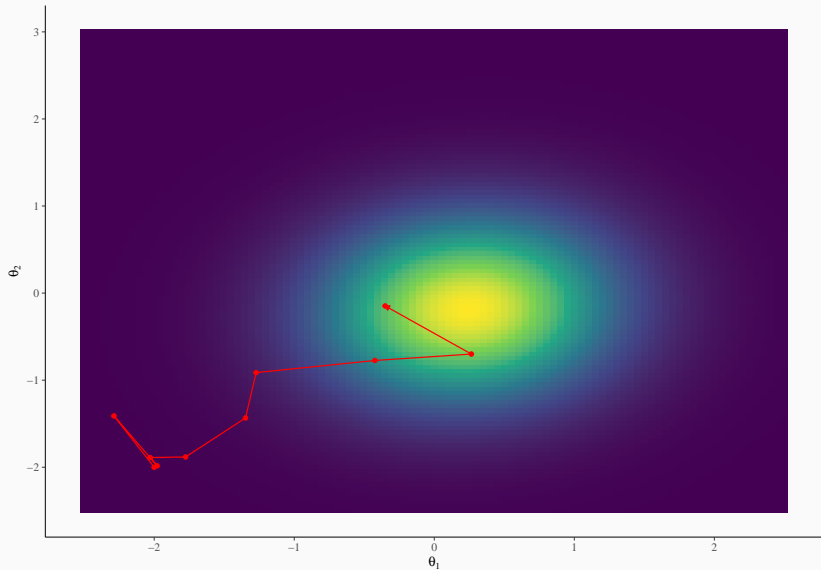
## We can't simply draw samples from the posterior

A Markov Chain is a sequence of values where the value at position  $s$  is based only on the former value at position  $s - 1$ :

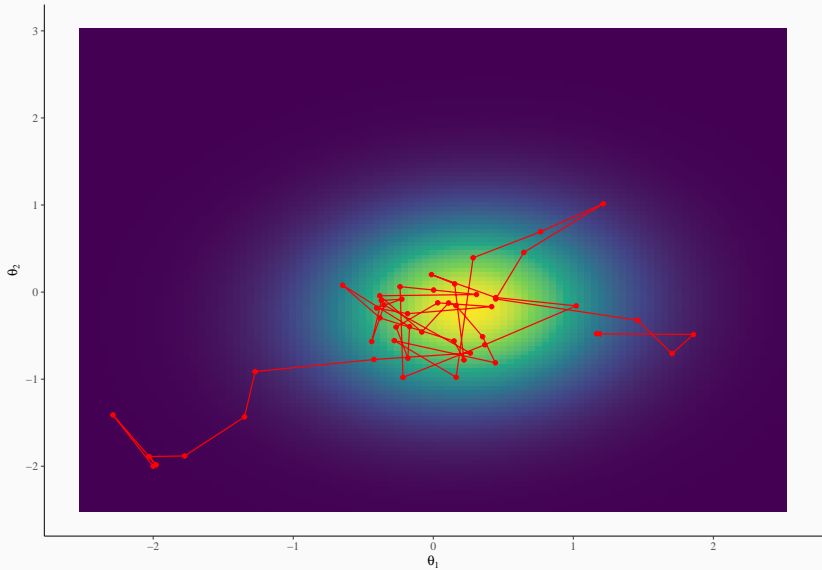
$$\theta^{(1)} \rightarrow \theta^{(2)} \rightarrow \theta^{(3)} \rightarrow \dots \rightarrow \theta^{(S)}$$

If the *transition distribution* is set up correctly, the values  $\theta^{(1)}, \dots, \theta^{(S)}$  will represent (dependent) samples from the posterior

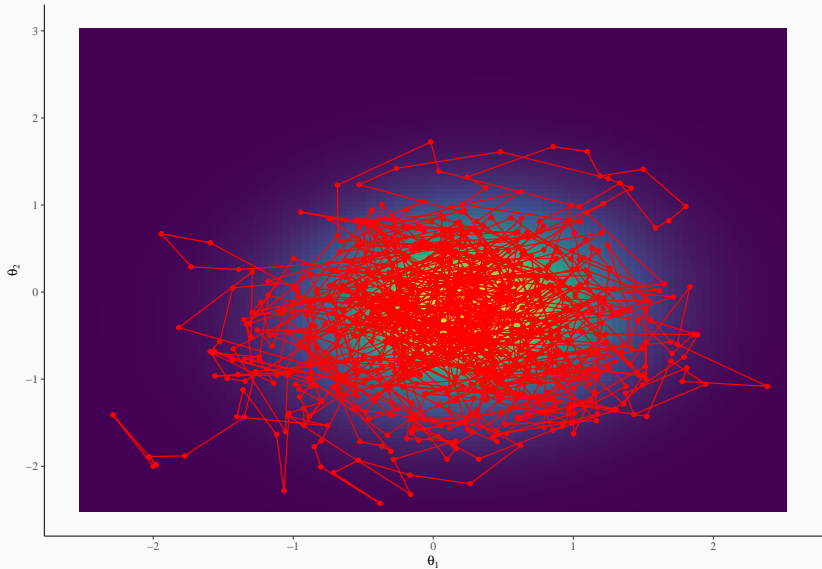
# MCMC Sampling: A Single Chain (10 Iterations)



# MCMC Sampling: A Single Chain (50 Iterations)



# MCMC Sampling: A Single Chain (1000 Iterations)

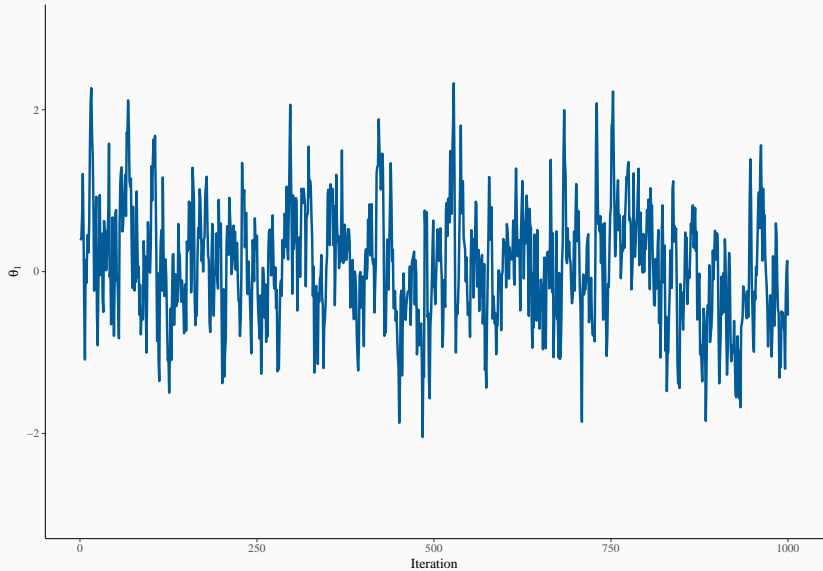


**MCMC samples can be used to approximate expectations**

Assume well-behaved MCMC samples  $\{\theta^{(s)}\}$  over  $p(\theta | y)$ :

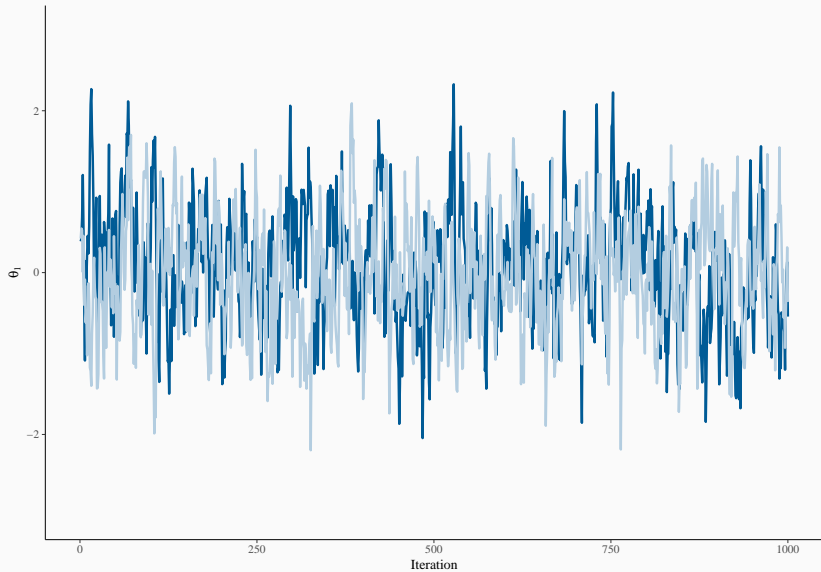
$$\frac{1}{S} \sum_{s=1}^S f(\theta^{(s)}) \sim \text{Normal} \left( \mathbb{E}_{\theta|y}(f), \sqrt{\frac{\text{Var}_{\theta|y}(f)}{\text{ESS}}} \right)$$

# Trace Plots: Visualizing a Single Chain



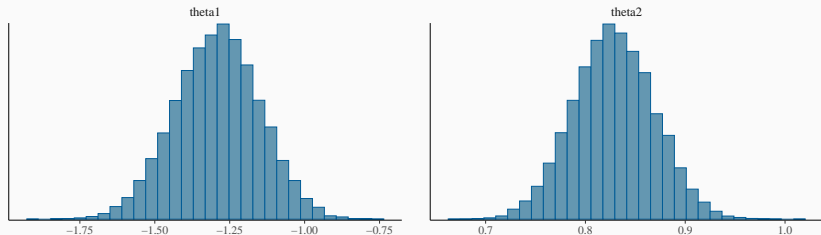


# Trace Plots: Visualizing Multiple Chains





# Catching Fish: Results

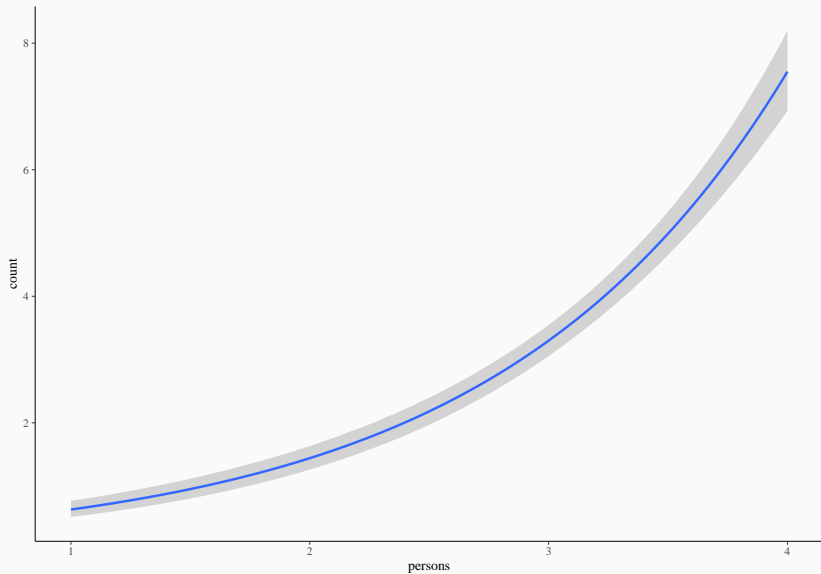


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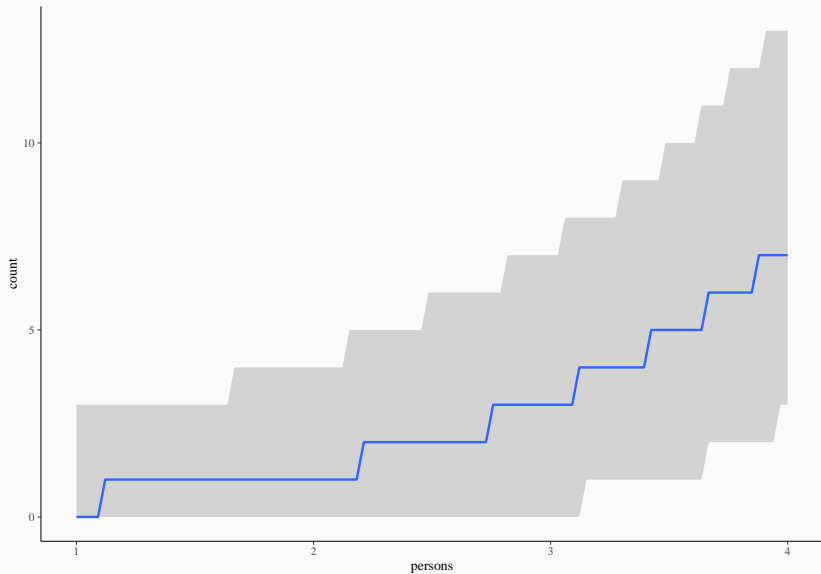
variable	mean	median	sd	q5	q95
theta1	-1.29	-1.29	0.14	-1.53	-1.06
theta2	0.83	0.83	0.04	0.76	0.90

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# Catching Fish: Expected posterior predictions



# Catching Fish: Posterior prediction



# What I like and don't like about Bayesian inference

What I like:

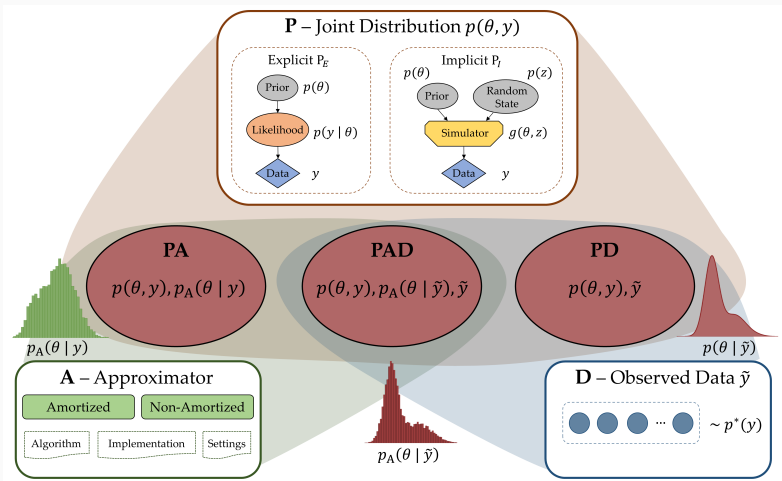
- Intuitive approach to expressing uncertainty
- Ability to incorporate prior information
- A lot of modeling flexibility
- Joint posterior distribution of parameters
- Easy propagation of uncertainty

What I don't like:

- Slow Speed of model estimation

# A brief look into my own research

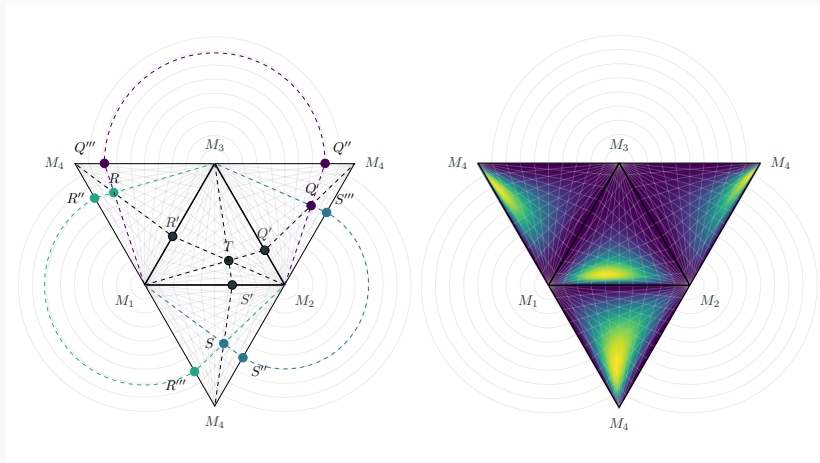
# What actually is a Bayesian Model?





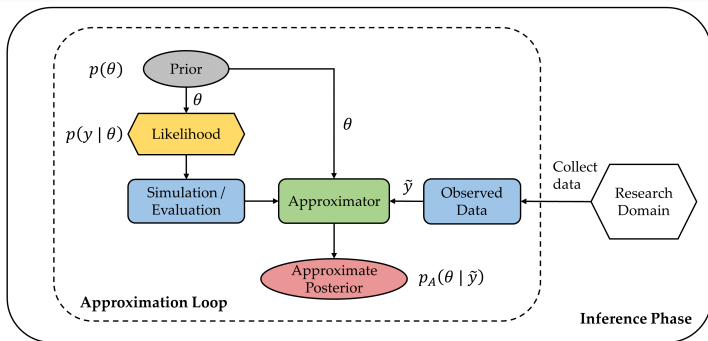
# Uncertainty of Uncertainty (Meta-Uncertainty)

How can we combine Bayesian and frequentist uncertainties?



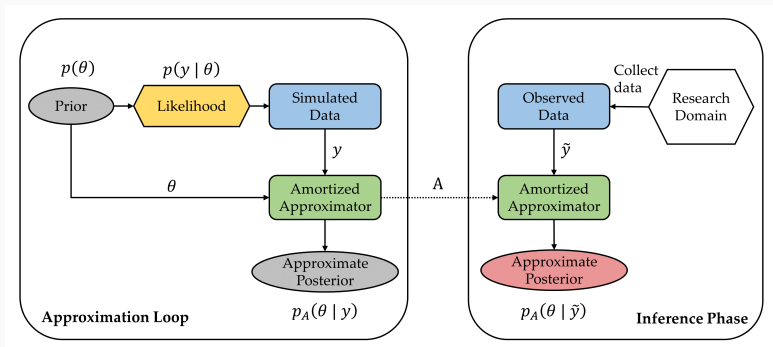
# Non-Amortized (Standard) Inference

How can we improved the standard inference setting?



# Amortized Inference

How far can we scale amortized inference?



## More about me and my research



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